Scalable Statistical Tools for Social Data Analysis

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- Online Social Networks (OSNs) such as Facebook, Twitter or Google+ have rapidly become the most popular online services. (Hundreds of millions of users intensively interact every day).
- OSNs have an invaluable channel of information for different sectors such as advertising, marketing or politics.
- Important unsolved problem: the identification of relevant users.
- Why? They will be the users to be addressed in order to advertise a product, propagate a message, improve the image of a company,...

- The research community in OSNs is focusing on identifying metrics that best define influential users.
- Most existing works pre-define the properties of the target users to be found, and based on such definition, they establish ad-hoc mechanisms to find the target users. (Supervised techniques)
- Two main drawbacks:
 - **()** They require a considerable manual analysis of the problem and the data.
 - Their effectiveness is fully tied with the definition of the target users' profile. (Results would be likewise inaccurate or incorrect).
- **General Objective**:Unsupervised methods for the detection of relevant users are required to advance in the state-of-the-art of this important field.

- We have a dataset of 10 million Google+ users and their associated public activity during two years (Jun 2011-July 2013). (González et al. (2015))
- Each user (or agent) is represented by 23 different variables covering connectivity, activity and user profile information including:
 - **Over a set of a set**
 - Number of published posts: it characterizes the level of activity of a user in the network.
 - Number of received likes, reshares and comments to the users' posts: They characterize the influence capacity of a user to create engagement.
- We have removed all users in our dataset with less than 10 public posts over a period of 2 years. (They are "consumers" but not relevant).
- Final size of the dataset after applying the filtering: **5.619.786 users**.

From the dataset to a statistical challenge

- When multivariate data have more than three dimensions, it is practically impossible to graphically visualize the observations using Cartesian coordinates.
- Convenient alternative: parallel coordinates (Wegman (1990)).

A multivariate point \equiv a series of points in the plane connecting each pair of adjacent points by a line.

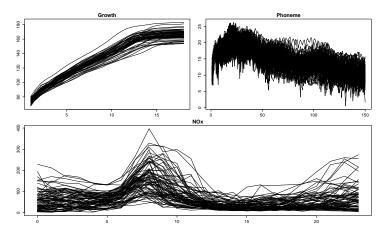
Once represented by means of parallel coordinates, observations x ∈ ℝ^d can be seen as real functions defined on an arbitrary set of equally spaced domain points, e.g., {1,...,d}, and x can be expressed as x = {x(1),...,x(d)}. (López-Pintado and Romo (2009)).

From the dataset to a statistical challenge

- Observations can be represented as curves ⇒ We can use the tools provided by an area of statistics known as Functional data analysis (FDA) (Ramsay and Silverman (2005), Ferraty and Vieu (2006), Horváth and Kokoszka (2012) or Cuevas (2014)).
- In the FDA framework, it is common to assume that:
 - Observations are generated by a functional random variable $X \in \mathbb{F}$, where \mathbb{F} is a functional space.
 - Or X is as a stochastic process $\{X(t), t \in I\}$, where I is an interval in \mathbb{R} .
- Three functional real datasets:
 - Growth data (girls): growth curves of 54 heights of girls measured at a common discretized set of 31 nonequidistant ages between 1 and 18 years.
 - Phoneme data ("aa"): 100 log-periodograms of length 150 corresponding to recordings of speakers pronouncing the phoneme "aa".
 - NO_x data (working days): 76 nitrogen oxides (NO_x) emission level daily curves measured every hour near to an industrial area in Poblenou (Barcelona).

Functional data examples

Figure: growth data (top left), phoneme data (top right), NO_x data (bottom)



Who is a relevant user in the dataset?

An atypical observation \equiv Outlier

• Our proposal: Relevant users in OSNs can be viewed as outliers in FDA.

(They usually show behaviors and patterns that are different from the ones of non-relevant commons users)

• Our methodology can be used to search for potentially relevant Google+ users, whose identification will be based on a statistical criterion but not by directed arguments. **(Unsupervised)** (Cha et al. (2010); Bakshy et al. (2011); Simmie et al. (2014); Basaras et al. (2013)).

BUT...

- Formal definition?: An outlier can be defined as an observation generated by a functional random variable with a different distribution from the one generating the normal observations of a functional sample (Febrero et al. (2008)).
- We focus on the three types of persistent outliers defined by Hubert et al. (2015):
 - Shift/magnitude outliers ≡ those who have the same shape of the majority but are moved away.
 - Amplitude outliers ≡ curves that may have the same shape as the majority but their scale differs.
 - **③** Shape outliers \equiv curves whose shape differs from the majority.

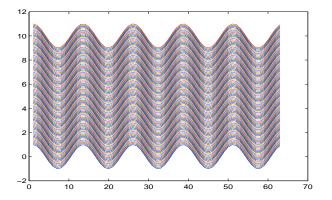


Figure: Functional sample without outliers.

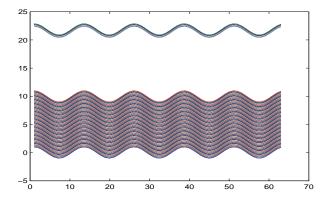


Figure: Functional sample with magnitude outliers.

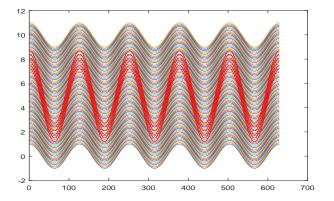


Figure: Functional sample with amplitude outliers.

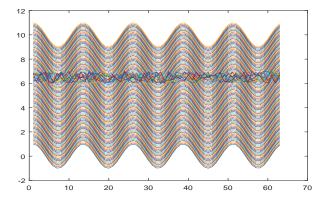


Figure: Functional sample with shape outliers.

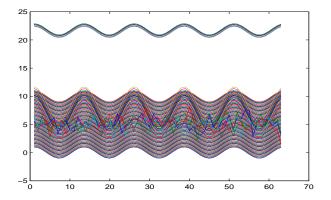
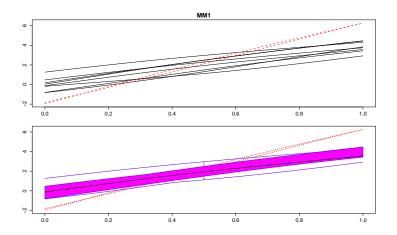


Figure: Functional sample with magnitude, amplitude and shape outliers.

- There are several methods to detect an outlier in FDA.
- Some of them are based on the use of measures known as **functional depths**: A measure that allows to order and rank the observations in a functional sample from the most to the least central.
 - High values to central observations.
 - Low values to non-central observations.
- Unlike univariate statistics where ℝ provides a natural order criterion for observations, several criteria have been employed to order functional data
 ⇒ there exist different implementations of the notion of functional depth (see Sguera et al. (2014)).

Our competitors: Functional boxplot

Functional boxplot (*FBPLOT*, Sun and Genton (2011)): 50%-central region (smallest band containing at least half of the deepest curves) factor non-outlying region = 1.5, functional depth = Modified band depth.



Our competitors: Two bootstrap-based procedures

- Febrero et al. (2008) proposed two depth-based outlier detection procedures selecting a **threshold** for the h-modal depth (Cuevas et al. (2006)).
- The threshold is obtained through two alternative robust smoothed bootstrap procedures whose single bootstrap samples are obtained using:
 - B_{tri}: the resampling is done on a trimmed version of the original sample, that is, after deleting from the sample a given proportion of least deep curves (trimmed resampling).
 - B_{wei}: the resampling is done giving weights to sample observations that are proportional to their depth values (weighted resampling).
- At each bootstrap sample, the 1% percentile *p*_{0.01} of the empirical distribution of the depth values is obtained.
- Let *B* be the number of bootstrap samples:

threshold \rightarrow median of the *B*-sized collection of $p_{0.01}$

• Except for the computation of the threshold, both procedures are iterative.

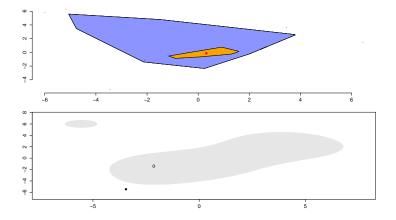
Our competitors: Robust FPCA-based procedures

- FBAG, Functional Bagplot (Hyndman and Shang (2010)):
 - Reduces the outlier detection problem from functional to multivariate by means of the functional principal component analysis technique.
 - Once obtained the first two functional principal components scores, FBAG orders the scores using the multivariate halfspace depth (Tukey (1975)) and builds a non-outlying region.
 - FBAG detects as outliers those observations whose scores are outside the non-outlying region.
- FHDR Functional hig densisty region boxplot (Hyndman and Shang (2010)):
 - Procedure that differs from FBAG after obtaining the first two functional principal components scores.
 - FHDR performs a bivariate kernel density estimation on the scores and defines a high density region.
 - FHDR detects as outliers those observations whose scores are outside the high density region.

Our competitors: Robust FPCA-based procedures

Functional bagplot (FBAG): 50%-central region, factor non-outlying region = 2.58, bivariate depth = halfspace depth (top);

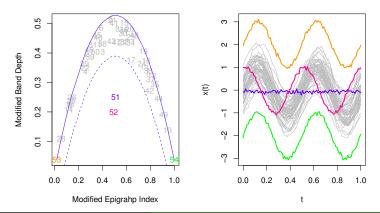
Functional high density region boxplot (FHDR): 90%-high density region (bottom)



Our competitors: The outliergram

Outliergram (*OG*, Arribas-Gil and Romo (2014)): depth-based outlier detection method based on a visualization tool known as outliergram.

OG exploits the relation between the modified band depth (López-Pintado and Romo (2009)) and the modified epigraph index (López-Pintado and Romo (2011)) to help understanding shape features of observations.



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Our competitors: Probabilistic methods

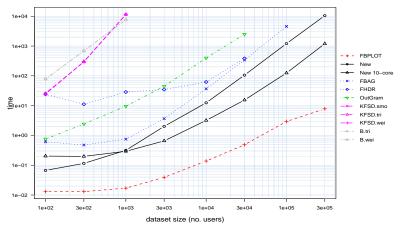
- *KFSD_{smo}*, *KFSD_{tri}* and *KFSD_{wei}* (Sguera et al. (2015)): depth-based outlier detection methods which select the threshold of the kernelized functional spatial depth (KFSD, Sguera et al. (2014)) by means of a probabilistic procedure based on three alternative resampling techniques that differ in their resampling steps:
 - KFSD_{smo}: the resampling is simple and smoothed, that is, once an observation is sampled, a small perturbation is added to the observation to avoid repeated observations.
 - Section 2012 KFSD_{tri}: the resampling is trimmed and smoothed.
 - Solution KFSD_{wei}: the resampling is weighted and smoothed.

What is the problem of these methods for Big Data?

They are not scalable!!

- We have tested all these methods with random samples of our dataset in order to observe the time performance.
- Experiments have been carried out in an AMD Opteron 6276 x64 cores @ 2.3GHz with 512GiB of RAM under Debian 7.9.
- We ran our method with one single partition, and using 10 partitions in order to check the scalability and verified that the time performance decreased by one order of magnitude.

What is the problem of these methods for Big Data?



Time Performances for the algorithms

Figure: Time performance for the different algorithms (log-log scale). The new method appears twice, with 1 core and 10 cores

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We introduce **three indexes** that can be interpreted as similarity measures of an observation with respect to a sample, and each one of them focus on a different feature of the data: magnitude, amplitude or shape.

Let $\mathcal{X} = \{x_1, x_2, \dots, x_n\}$ be a set of *n* curves whose common discretized form is defined on a given set of *d* equally spaced domain points, and *x* be another curve defined on the same set.

• The shape index of x with respect to \mathcal{X} is defined as

$$I_{\mathcal{S}}(x,\mathcal{X}) = \left| \frac{1}{n} \sum_{j=1}^{n} \rho(x,x_j) - 1 \right|,$$

where $\rho(x, x_j)$ is the Pearson correlation coefficient between the discretized versions of x and x_j .

The shape index

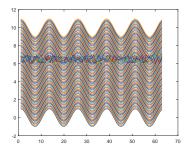


Figure: Functional sample with shape outliers.

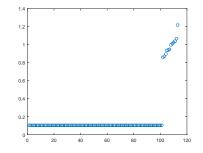


Figure: $I_S(x, \mathcal{X})$ -based ranks versus $I_S(x, \mathcal{X})$ values.

Let α_j and β_j be the estimated intercept and the slope of a linear regression model where the discretized version of x represents the observed values of the dependent variable and the discretized version of x_j represents the observed values of the regressor.

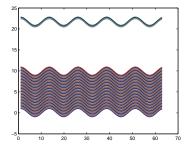
• We define the **magnitude index** of x with respect to \mathcal{X} as

$$U_M(x,\mathcal{X}) = \left| \frac{1}{n} \sum_{j=1}^n \alpha_j \right|,$$

• And the **amplitude index** of x with respect to \mathcal{X} as

$$I_A(x,\mathcal{X}) = \left| \frac{1}{n} \sum_{j=1}^n \beta_j - 1 \right|.$$

The magnitude index



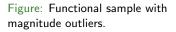
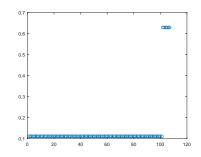


Figure: $I_M(x, \mathcal{X})$ -based ranks versus $I_M(x, \mathcal{X})$ values.



The amplitude index

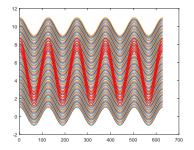


Figure: Functional sample with amplitude outliers.

Figure: $I_A(x, \mathcal{X})$ -based ranks versus $I_A(x, \mathcal{X})$ values.

80 100

120

16 14

12

10 8 6

2

20 40 60

Next problem: Which are the outliers curves?

• Normalize the indexes as follows. Let $I_S(\mathcal{X}) = \{I_S(x_1, \mathcal{X}), \dots, I_S(x_n, \mathcal{X})\}$ be the vector of the shape indexes and, analogously, let $I_M(\mathcal{X})$ and $I_A(\mathcal{X})$ be the vectors of the magnitude and amplitude indexes respectively. Hereafter we will use $I(\mathcal{X})$ for any of the three vectors of indexes indistinctly. We use the ∞ -norm for vectors and we define

$$\hat{I}_{\mathcal{X}} = \frac{I(\mathcal{X})}{||I(\mathcal{X})||_{\infty}} = \left\{ \frac{I(x_1, \mathcal{X})}{||I(\mathcal{X})||_{\infty}}, \cdots, \frac{I(x_n, \mathcal{X})}{||I(\mathcal{X})||_{\infty}} \right\},$$

where $\hat{l}_{\mathcal{X}}$ is the normalized vector of indexes and $|| \cdot ||_{\infty} = \max(\cdot)$.

- Normalization \implies using $\hat{l}(\mathcal{X}) \in [0, 1]$.
- Define the following function f.

$$egin{aligned} f \colon \{1..|\hat{l}_{\mathcal{X}}|\} &
ightarrow \hat{l}_{\mathcal{X}} \ f(i) &\mapsto \hat{l}_{\mathcal{X}}[i] \end{aligned}$$

where $\hat{I}_{\mathcal{X}}[i]$ is the index ranked in position *i* in increasing order.

Next problem: Which are the outliers curves?

• Define the *backward difference* for *f* as

$$\nabla_h[f](i) := f(i) - f(i-h).$$

Thus, we can establish the relationship between the derivative definition and the backward difference since

$$f'(i) = \lim_{h \to 0} \frac{f(i) - f(i-h)}{h} \equiv \lim_{h \to 0} \frac{\nabla_h[f](i)}{h}.$$

- Finally, we have computed the derivative function f' for our curve f and we are going to filter those values above a certain threshold value.
 - Given the threshold θ, it represents the maximum slope allowed for the derivative to be considered a "normal" value.
 - Otherwise, the derivative points (onwards) above this threshold are considered outliers.

Set of outliers
$$\equiv I_{\mathcal{X}}^{out} = \{I_{\mathcal{X}}[j] : f(j) > f(i_{\theta})\}$$

- We compare our methods with the competitors in functional outlier detection.
- Important question: Is our method competitive in the usual framework in FDA?
- For each model, 100 replications of size 100.
- Probability that each curve is an outlier ($\alpha = 0.05$)

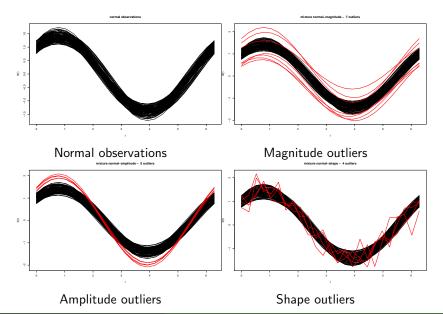
- $\mathbf{c} \equiv$ Correct outlier detection percentages.
- $\mathbf{f} \equiv$ False outlier detection percentages.
- **F**-measure \equiv the harmonic mean of precision and recall.

$$F=\frac{2RP}{R+P},$$

where $R = \frac{TP}{(TP+FN)}$ is known as recall measure, $P = \frac{TP}{TP+FP}$ is known as precision measure and TP, FN, and FP are the number of true positive, false negative and false positive, respectively.

• $\mathbf{r} \equiv F$ -measure-based rankings of the methods in the mixture models.

Models

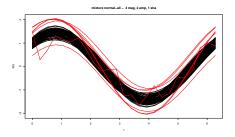


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Table: Correct outlier detection percentages (c), false outlier detection percentages (f), F-measures (F) and F-measure-based rankings of the methods (r) in mixture models 1, 2 and 3 which allow for magnitude (mag), amplitude (amp) and shape (sha) outliers, respectively.

	mag					am	p		sha			
	С	f	F	r	с	f	F	r	С	f	F	r
B _{tri}	54.55	0.00	0.71	6	16.67	0.01	0.29	9	83.82	0.00	0.91	2
B _{wei}	98.42	0.05	0.98	1	25.00	0.01	0.40	8	100.00	0.00	1.00	1
FBAG	3.16	0.27	0.06	10	91.67	0.46	0.91	2	8.29	0.24	0.14	11
FHDR	15.61	4.43	0.16	9	75.97	1.14	0.77	6	24.08	3.96	0.24	10
FBPLOT	39.13	0.00	0.56	8	0.39	0.00	0.00	11	64.55	0.00	0.79	9
OG	0.00	0.00	-	-	0.78	0.00	0.02	10	0.00	0.00	-	-
KFSD _{smo}	98.81	0.09	0.98	1	82.17	0.11	0.89	3	84.39	0.13	0.90	3
KFSD _{tri}	99.60	2.51	0.81	4	96.90	2.35	0.81	5	99.23	2.45	0.81	6
KFSD _{wei}	100.00	2.71	0.80	5	97.48	2.13	0.82	4	99.81	2.66	0.80	7
new	96.05	5.84	0.63	7	96.71	6.54	0.61	7	95.18	1.60	0.84	5
new _{mag}	95.85	0.50	0.93	3	0.00	2.21	-	-	68.98	0.16	0.80	7
new _{amp}	0.59	0.93	0.01	12	96.71	0.62	0.93	1	4.62	0.98	0.08	12
new _{sha}	4.94	4.79	0.05	11	0.00	5.62	-	-	83.04	0.50	0.86	4

Mixing types of outliers



		all								
	с	f	F	r						
B _{tri}	61.81	0.00	0.77	6						
B _{wei}	96.21	0.00	0.98	1						
FBAG	35.32	0.26	0.50	9						
FHDR	42.32	3.00	0.42	11						
FBPLOT	34.92	0.00	0.52	8						
OG	0.52	0.00	0.02	13						
KFSD _{smo}	82.67	0.14	0.89	2						
KFSD _{tri}	99.35	2.34	0.82	4						
KFSD _{wei}	99.80	2.51	0.81	5						
new	97.58	2.01	0.83	3						
new _{mag}	41.33	0.08	0.57	7						
new _{amp}	34.01	0.37	0.48	10						
new _{sha}	30.22	1.61	0.37	12						

Table: Decomposed correct outlier detection percentages in mixture model 4 allowing simultaneously for magnitude (mag), amplitude (amp) and shape (sha) outliers.

	mag					amp)		shape			
	с	f	F	r	с	f	F	r	с	f	F	r
B _{tri}	73.08	1.92	0.52	3	21.40	2.84	0.14	9	89.98	1.65	0.63	1
B _{wei}	100.00	3.23	0.52	3	88.60	3.49	0.45	4	99.80	3.27	0.52	4
FBAG	0.77	2.07	0.01	10	98.40	0.42	0.88	2	8.64	1.94	0.08	11
FHDR	8.65	4.94	0.04	9	98.00	3.42	0.49	3	22.00	4.71	0.11	10
FBPLOT	40.19	1.10	0.39	6	1.00	1.79	0.01	11	62.87	0.73	0.61	3
OG	0.00	0.03	-	-	1.60	0.00	0.04	10	0.00	0.03	-	-
KFSD _{smo}	100.00	2.66	0.57	2	69.80	3.24	0.39	5	77.60	3.09	0.43	5
KFSD _{tri}	100.00	5.64	0.39	6	98.40	5.74	0.37	7	99.61	5.69	0.37	6
KFSD _{wei}	100.00	5.84	0.37	8	99.80	5.91	0.36	8	99.61	5.88	0.37	6
new	100.00	5.23	0.40	5	100.00	5.30	0.39	5	92.73	5.39	0.37	6
newmag	100.00	0.46	0.88	1	1.80	2.19	0.01	11	20.24	1.87	0.18	9
newamp	0.00	2.12	-	-	100.00	0.43	0.89	1	3.93	2.05	0.03	12
new _{sha}	1.35	3.10	0.01	10	0.00	3.12	-	-	89.39	1.58	0.63	1

Focusing on shape outliers

Models used in Arribas-Gil and Romo (2014) to evaluate OG.

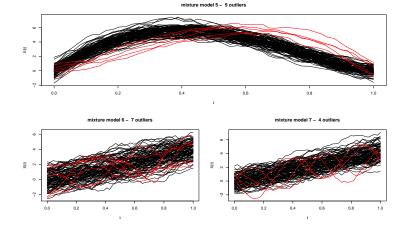


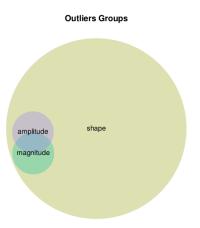
Figure: Mixture models 5 (top), 6 (bottom left) and 7 (bottom right).

Table: Correct outlier detection percentages (c), false outlier detection percentages (f), F-measures (F) and F-measure-based rankings of the methods (r) in mixture models 5, 6 and 7.

	mix mod 5					mix mo	od 6		mix mod 7			
	с	f	F	r	с	f	F	r	с	f	F	r
B _{tri}	48.23	0.03	0.65	10	26.20	0.59	0.38	8	23.55	0.79	0.34	8
B _{wei}	88.08	0.41	0.90	2	30.59	0.71	0.43	7	23.55	0.76	0.35	7
FBAG	99.63	6.70	0.63	11	36.14	7.00	0.27	9	8.58	7.86	0.06	10
FHDR	65.74	1.55	0.68	8	23.71	3.97	0.24	10	5.59	4.97	0.06	10
FBPLOT	26.44	0.01	0.41	13	0.19	0.00	0.00	13	0.40	0.02	0.00	13
OG	97.95	2.31	0.82	4	98.85	3.36	0.76	1	100.00	3.92	0.73	1
KFSD _{smo}	84.92	0.55	0.87	3	49.52	3.05	0.48	5	45.71	3.67	0.43	5
KFSD _{tri}	98.14	4.36	0.71	7	79.54	6.29	0.54	4	82.04	6.33	0.55	3
KFSD _{wei}	99.26	5.27	0.68	8	86.81	7.02	0.56	3	88.22	7.22	0.54	4
new	95.53	3.42	0.75	5	67.30	6.91	0.46	6	67.66	7.47	0.44	5
newmag	47.49	1.65	0.53	12	9.37	3.17	0.11	12	1.00	3.92	0.01	12
newamp	72.63	1.60	0.72	6	14.53	3.49	0.17	11	6.19	3.75	0.07	9
new _{sha}	92.74	0.53	0.92	1	60.04	2.24	0.60	2	66.07	2.15	0.64	2

Going back to the OSN problem

After applying the outlier detection method, we obtain 285.804, 4.270 and 4.434 "relevant" users based on the shape, amplitude, magnitude metrics.



Are the users detected as outliers different?

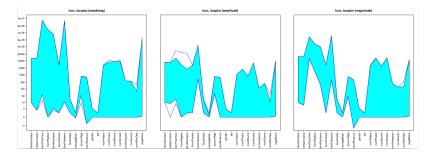


Figure: Functional boxplots

Are the users detected as outliers different?

- In order to discuss the "relevance" of outliers, we rely on metrics measuring the ratio of number of reactions (likes, comments and shares) per activity (post) ⇒ capture the ability of a user to generate engagement.
 - Our methodology is efficient since users identified in the three groups present 1 or 2 order of magnitude more reaction per activity than regular users. (More engagement)
 - The amp&mag group shows roughly one order of magnitude more reactions per activity than amp outliers.
 - **The difference is smaller when comparing** *amp&mag group* vs. *mag.*

Are the users detected as outliers different?

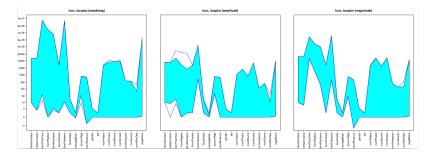


Figure: Functional boxplots

Type of relevant users



Median amplitude

Jesse & Joy



Median magnitude

Amplitude-magnitude outliers

- We have converted a **Big Problem** in OSN to a **Statistical Problem with Big Data**.
- Relevant users are considered as outlier in Functional Data.
- We have introduced a new method to detect outliers that distinguishes amplitude, shape and magnitude outliers and besides; it is:
 - Ompetitive respect to performance.
 - Scalable for big data.
- The evaluation of our method in a real OSN dataset provides solid evidences about its ability to identify relevant agents in real cases.
- We obtain interesting results with semantic interpretation.

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