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# Interval Arithmetic: Fundamentals, Successes, and Pitfalls

# Ralph Baker Kearfott

Department of Mathematics University of Louisiana at Lafayette

# Universidad EAFIT, Friday, July 27, 2018



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► Operations are defined over the set of closed and bounded intervals *x* = [*x*, *x*].



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### conclusion

► Operations are defined over the set of closed and bounded intervals *x* = [*x*, *x*].

► The result of the operation is defined logically for  $\odot \in \{+, -, \times, \div\}$  as  $\mathbf{x} \odot \mathbf{y} = \{\mathbf{x} \odot \mathbf{y} \mid \mathbf{x} \in \mathbf{x} \text{ and } \mathbf{y} \in \mathbf{y}\}.$ 



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- ► The result of the operation is defined logically for  $\odot \in \{+, -, \times, \div\}$  as  $\mathbf{x} \odot \mathbf{y} = \{\mathbf{x} \odot \mathbf{y} \mid \mathbf{x} \in \mathbf{x} \text{ and } \mathbf{y} \in \mathbf{y}\}.$
- The logical definition leads to operational definitions:  $\mathbf{x} + \mathbf{y} = [\underline{x} + \underline{y}, \overline{x} + \overline{y}],$

 $\boldsymbol{x} - \boldsymbol{y} = [\underline{x} - \overline{y}, \overline{x} - \underline{y}],$ 

 $\mathbf{x} \div \mathbf{y} = \mathbf{x} \times -\mathbf{y}$ 

 $\boldsymbol{x} \times \boldsymbol{y} = [\min\{\underline{x}\underline{y}, \underline{x}\overline{y}, \overline{x}\underline{y}, \overline{x}\overline{y}\}, \max\{\underline{x}\overline{y}, \underline{x}\overline{y}, \overline{x}\underline{y}, \overline{x}\overline{y}\}]$ 

$$\frac{1}{x} = \begin{bmatrix} \frac{1}{\overline{x}}, \frac{1}{\underline{x}} \end{bmatrix} \quad \text{if } \underline{x} > 0 \text{ or } \overline{x} < 0$$

(There are alternatives for  $\times$  and  $\div$  more efficient for certain architectures.)



## Classical Interval Arithmetic What does this definition do?

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### conclusion

In exact arithmetic, the operational definitions give the exact ranges of the elementary operations.



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# Classical Interval Arithmetic What does this definition do?

- In exact arithmetic, the operational definitions give the exact ranges of the elementary operations.
- Evaluating an expression in interval arithmetic does not give an exact range of the expression, but does give bounds on the range of the expression.



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# Classical Interval Arithmetic What does this definition do?

- In exact arithmetic, the operational definitions give the exact ranges of the elementary operations.
- Evaluating an expression in interval arithmetic does not give an exact range of the expression, but does give bounds on the range of the expression.
- Example (interval dependence)

If f(x) = (x + 1)(x - 1), then

$$f([-2,2]) = ([-2,2]+1)([-2,2]-1) = [-1,3][-3,1] = [-9,3],$$

whereas the exact range is [-1,3].



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- Example (interval dependence)

If f(x) = (x + 1)(x - 1), then

$$\begin{split} f([-2,2]) &= ([-2,2]+1)([-2,2]-1) \\ &= [-1,3][-3,1] = [-9,3], \end{split}$$

whereas the exact range is [-1,3].

► The interval [-9, 3] represents the exact range of  $\tilde{f}(x, y) = (x + 1)(y - 1)$  over the rectangle  $x \in [-2, 2]$ ,  $y \in [-2, 2]$  (when x and y vary independently).



Why can this be mathematically rigorous with approximate arithmetic?

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► The operational definitions give approximate end points.



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- ► The operational definitions give approximate end points.
- Modern computational environments (such as IEEE 754-compliant ones) allow rounding down to the nearest machine number less than the exact result and rounding up to the nearest machine number greater than the exact result.



Why can this be mathematically rigorous with approximate arithmetic?

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- ► The operational definitions give approximate end points.
- Modern computational environments (such as IEEE 754-compliant ones) allow rounding down to the nearest machine number less than the exact result and rounding up to the nearest machine number greater than the exact result.
- If we use downward rounding to compute the lower end point and upward rounding to compute the upper end point, the result of each elementary operation contains the exact range of that operation.



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- If we use downward rounding to compute the lower end point and upward rounding to compute the upper end point, the result of each elementary operation contains the exact range of that operation.
- Hence, an interval evaluation of an expression on a machine mathematically rigorously contains the range of the expression.



# Algebraic Properties (or lack thereof)

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# Interval arithmetic is commutative and associative.



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- Interval arithmetic is commutative and associative.
- ► There are no additive and multiplicative inverses.



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### conclusion

# Interval arithmetic is commutative and associative.

**Algebraic Properties** 

(or lack thereof)

There are no additive and multiplicative inverses.

For example: 
$$\begin{bmatrix} 1,2 \\ - & [1,2] \end{bmatrix} = \begin{bmatrix} -1,1 \\ 1,2 \end{bmatrix}$$
 
$$\begin{bmatrix} 1,2 \\ - & [1,2] \end{bmatrix} = \begin{bmatrix} \frac{1}{2},2 \end{bmatrix}$$



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# Interval arithmetic is commutative and associative.

**Algebraic Properties** 

(or lack thereof)

► There are no additive and multiplicative inverses.

Interval arithmetic is only subdistributive: a(b + c) ⊆ ab + ac.



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### conclusion

- Interval arithmetic is commutative and associative.
- There are no additive and multiplicative inverses.

Interval arithmetic is only subdistributive: a(b + c) ⊆ ab + ac.

### For example,

[-1, 1]([-3, -2] + [2, 3]) = [-1, 1][-1, 1] = [-1, 1], while [-1, 1][-3, -2] + [-1, 1][2, 3] = [-3, 3] + [-3, 3] = [-6, 6].

# Algebraic Properties (or lack thereof)



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# ► Theorem (Single Use Expressions — SUE)

In an algebraic expression evaluated in exact interval arithmetic, the result is the exact range if each variable occurs only once in the expression.



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# Interval arithmetic is commutative and associative.

Algebraic Properties

There are no additive and multiplicative inverses.

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# ► Theorem (Single Use Expressions — SUE)

In an algebraic expression evaluated in exact interval arithmetic, the result is the exact range if each variable occurs only once in the expression.

• Note: The converse is not true.



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Midpoint-radius arithmetic: Intervals represented in terms of midpoint and error; addition gives exact range but multiplication just gives an enclosure for the range.



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Midpoint-radius arithmetic: Intervals represented in terms of midpoint and error; addition gives exact range but multiplication just gives an enclosure for the range.

Circular arithmetic: Representation as midpoint-radius, but with the midpoint in the complex plane. Elementary operations are not exact, but are mere enclosures.



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Rectangular arithmetic: An alternative complex interval arithmetic. Addition is exact, but multiplication just gives an enclosure.



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Rectangular arithmetic: An alternative complex interval arithmetic. Addition is exact, but multiplication just gives an enclosure.

Kaucher arithmetic, modal arithmetic etc.: Algebraically completes interval arithmetic with additive inverses. It has uses, but interpretation of the results is more complicated, sometimes depending on monotonicity properties.



### Interval Arithmetic (IA) Fundamentals

# Consider $\frac{x}{v} = [1,2]/[-3,4].$

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### conclusion

► In our operational definition,  $\frac{1}{v} = \begin{bmatrix} \frac{1}{4}, -\frac{1}{3} \end{bmatrix}$ ???



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Consider  $\frac{x}{v} = [1,2]/[-3,4].$ 

► The arguments contain undefined quantities <sup>a</sup>/<sub>0</sub> for a ∈ [1,2], but ...



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Consider  $\frac{x}{v} = [1,2]/[-3,4].$ 

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- ► The range of the operation over defined quantities is  $\left(-\infty, -\frac{1}{3}\right] \bigcup \left[\frac{1}{4}, \infty\right)$ .



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- ► The range of the operation over defined quantities is (-∞, -<sup>1</sup>/<sub>3</sub>] ∪ [<sup>1</sup>/<sub>4</sub>,∞).
- Different definitions for the operation's result and different interpretations are appropriate in different contexts. (More to be said later.)



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- Different definitions for the operation's result and different interpretations are appropriate in different contexts. (More to be said later.)
- This has been carefully considered and defined in an exception-tracking framework in the IEEE 1788-2015 standard for interval arithmetic.





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### conclusion

The same basic interval operations described in all of the early work, although it was apparently done independently.





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Paul S. Dwyer (Chapter in *Linear Computations*, 1951)



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Paul S. Dwyer (Chapter in *Linear Computations*, 1951) "Computation with Approximate Numbers." Interval computations are introduced as an integral part of roundoff error analysis.



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Mieczyslaw Warmus (Calculus of Approximations, 1956)



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Paul S. Dwyer (Chapter in *Linear Computations*, 1951) "Computation with Approximate Numbers." Interval computations are introduced as an integral part of roundoff error analysis.

Mieczyslaw Warmus (*Calculus of Approximations*, 1956) The motivation is apparently to provide a sound theoretical backing to numerical computation.



# (from a talk on the Origin of Intervals by Siegfried Rump)

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# conclusion

► a 1900 book Lectures on Numerical Computing (in German) with error bounds for +, -, ·, / and innacurate input data;



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- ► a 1900 book Lectures on Numerical Computing (in German) with error bounds for +, -, ·, / and innacurate input data;
- an 1896 article "On computing with inexact numbers" (in German) in the *Journal for Junior Highschool Studies*, giving the impression interval computations were standard fare in middle schools;



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- 1887, 1879, and 1854 French work where explicit formulas for the elementary operations and rigorous error bounds were given;



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- 1887, 1879, and 1854 French work where explicit formulas for the elementary operations and rigorous error bounds were given;
- An 1809 work by Gauß in Latin where explicit computation of error bounds, including rounding errors, appears.



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History of Interval Arithmetic

(beginning of the era of modern computers)



# History of Interval Arithmetic

(beginning of the era of modern computers)

Teruro Sunaga (RAAG Memoirs, 1958)

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# History of Interval Arithmetic It takes off.

(beginning of the era of modern computers)

Teruro Sunaga (RAAG Memoirs, 1958)

"Theory of an Interval Algebra and its Application to Numerical Analysis." Motivation is automatically accounting for uncertainty and error in measurement and computation.



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William Kahan Proposed extended interval arithmetic, saw to directed roundings in IEEE 754 and mentored several currently prominent students.



# History of Interval Arithmetic Others (Karlsruhe)

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# History of Interval Arithmetic Others (Karlsruhe)

# Rudolf Krawczyk published his famous Krawczyk method for existence / uniqueness proofs (1969)



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Siegfried Rump developed INTLAB, a Matlab toolbox for IA, and founded the Institute for Reliable Computing at Hamburg.



# History (Others)

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Interval



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Various locations in Russia Extensive publications.





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systems.

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#### Interval Arithmetic (IA) Fundamentals

# Rigorously bounding roundoff error in floating point computations.

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Rigorously bounding roundoff error in floating point computations.

Interval widths start out small, on the order of the machine precision, but ...



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Rigorously bounding roundoff error in floating point computations.

- Interval widths start out small, on the order of the machine precision, but ...
- overestimation can make results meaningless, and obtaining meaningful results is often tricky.



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Rigorously bounding roundoff error in floating point computations.

- Interval widths start out small, on the order of the machine precision, but ...
- overestimation can make results meaningless, and obtaining meaningful results is often tricky.

# Bounding function ranges over large domains

provides a polynomial-time computation that often gives helpful bounds, for ...



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  - proving the hypotheses of fixed point theorems,



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- provides a polynomial-time computation that often gives helpful bounds, for ...
  - proving the hypotheses of fixed point theorems,
  - bounding the objective function and proving or disproving feasibility in global optimization algorithms,



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  - proving collision avoidance in robotics, navigation systems, celestial mechanics,



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  - etc.



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# Proving Fixed Point Theorems Some Details

# Theorem (Brouwer fixed point theorem)

If g is a continuous mapping from a compact convex set **x** into itself, there is a fixed-point  $x \in \mathbf{x}$  of g, i.e. g(x) = x.



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▶ If we evaluate  $g : \mathbf{X} \subset \mathbb{R}^n \to \mathbb{R}^n$  over an interval vector  $\mathbf{X}$  and the interval value  $g(\mathbf{X}) \subseteq \mathbf{X}$ , this proves existence of a fixed point of g in  $\mathbf{X}$ .



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- If we evaluate g : x ⊂ ℝ<sup>n</sup> → ℝ<sup>n</sup> over an interval vector x and the interval value g(x) ⊆ x, this proves existence of a fixed point of g in x.
- Interval techniques based on this prove existence, uniqueness, and error bounds:



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## Proving Fixed Point Theorems

Some Details

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- Interval techniques based on this prove existence, uniqueness, and error bounds:
  - the Krawczyk method.
  - general interval Newton methods, such as the interval Gauss–Seidel method.



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 The Kepler Conjecture: (made by Johannes Kepler in 1611, proved with interval arithmetic by Thomas Hales)
 — no packing of spheres in 3-dimensional space is denser than face-centered cubic packing. See

https://en.wikipedia.org/wiki/Kepler\_conjecture.



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Chaos and attractors for the Lorenz equations: (a simplified ODE model of weather prediction).



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  - (and earlier) Mischaikov and Mrozek use Conley index theory and interval arithmetic to do the same.



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  - (and earlier) Mischaikov and Mrozek use Conley index theory and interval arithmetic to do the same.
  - Warwick Tucker (in dissertation work) used normal form theory and interval arithmetic to solve Stephen Smale's 14-th problem, namely, that the Lorenz equations have a persistent strange attractor.



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The R. E. Moore Prize for application of interval arithmetic has been awarded to various researchers. See http:

//www.cs.utep.edu/interval-comp/honors.html.
Among these are:



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Among these are:

2014 Kenta Kobayashi for Computer-Assisted Uniqueness Proof for Stokes' Wave of Extreme Form, and



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2018 Figueras, Haro, and Luque for Rigorous Computer-Assisted Application of KAM Theory: A Modern Approach



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2018 (a notable runner-up) Jean-Pierre Merlet for Simulation of discrete-time controlled cable-driven parallel robots on a trajectory



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These include:

1. Simple use of range bounds;



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These include:

- 1. Simple use of range bounds;
- Incorporation of range bounds in exhaustive domain searches (branch and bound algorithms) to enclose a global optimum of a minimization problem;

2. Stadtherr et al Correction of major errors in widely used tables of vapor-liquid equilibria.



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These include:

- 1. Simple use of range bounds;
- Incorporation of range bounds in exhaustive domain searches (branch and bound algorithms) to enclose a global optimum of a minimization problem;
- Incorporation of range bounds to rigorously enclose solution sets to differential equations in sophisticated mathematically rigorous ODE integrators.
- 2. Stadtherr et al Correction of major errors in widely used tables of vapor-liquid equilibria.
- 3. Berz et al Proof of stability of the beam, given assumed tolerances on the geometry and magnets, of the once-proposed superconducting supercollider (and the software continues to be used for other cyclotrons).

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### Luc Jaulin et al have used interval constraint propagation to increase both reliability and efficiency of underwater robot control and data analysis in generating maps. (Luc is the 2012 Moore Prize recipient.)



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- Luc Jaulin et al have used interval constraint propagation to increase both reliability and efficiency of underwater robot control and data analysis in generating maps. (Luc is the 2012 Moore Prize recipient.)
- (Earlier work continuing to the present) The forward manipulator problem (computation of joint angles for a particular robot hand location) is easily solved with exhaustive search (branch and bound) to the corresponding systems of nonlinear equations.



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- (Earlier work continuing to the present) The forward manipulator problem (computation of joint angles for a particular robot hand location) is easily solved with exhaustive search (branch and bound) to the corresponding systems of nonlinear equations.
- Interval arithmetic can be used in collision avoidance.



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Interval arithmetic can be used in collision avoidance.

In early work (1988) yours truly used Fortran-77-based software to show the set of published solutions to a manipulator problem posed by Alexander Morgan at General Motors was incorrect. This led to discovery of an incorrectly-given coefficient in the paper and to improvement in the software in use at General Motors.<sup>18/2</sup>



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### Pitfalls Where should interval arithmetic be used?

► Replacing floating point data types by intervals generally does not work. Due to interval dependency, this commonly results in output intervals of (∞, ∞).



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### Pitfalls Where should interval arithmetic be used?

- ► Replacing floating point data types by intervals generally does not work. Due to interval dependency, this commonly results in output intervals of (∞, ∞).
- Different algorithms are used for interval computations Also, different algorithms are used, depending on whether there are just small roundoff errors or large uncertainties in the data.



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- Rule of thumb: Use floating point computations where verification is not needed, and use intervals only to provide bounds in strategic places.



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- Rule of thumb: Use floating point computations where verification is not needed, and use intervals only to provide bounds in strategic places.
- ► Keep the interval computations as simple as possible.



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- ► Keep the interval computations as simple as possible.

The above considerations are how success is achieved.



#### Interval Arithmetic (IA) Fundamentals

Consider proving existence of a solution with the Brouwer fixed point theorem.

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Consider proving existence of a solution with the Brouwer fixed point theorem.

### Example



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Consider proving existence of a solution with the Brouwer fixed point theorem.

### Example

Consider  $g(x) = \sqrt{x-1} + 0.9$ , with a fixed point at  $x \approx 1.0127$  and  $x \approx 1.7873$ .

• On  $x \in [1.5, 2]$ , an interval evaluation gives  $g(x) \subseteq [1.6071, 1.9001] \subset [1.5, 2]$ , and we correctly conclude g has a fixed point in [1.6071, 1.9001]. However,  $\cdots$ 



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- if  $\mathbf{x} = [0, 1], \sqrt{x 1} = \sqrt{[-1, 0]}$  evaluates to [0, 0], so  $\mathbf{g}(\mathbf{x}) = [0.9, 0.9] \subset \mathbf{x}$ , for an incorrect conclusion.



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## Example

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- This is due to g not continuous on [0, 1], combined with loose evaluation (returning the range only over the intersection of the domain of g with the interval).



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Consider proving existence of a solution with the Brouwer fixed point theorem.

## Example

- On x ∈ [1.5,2], an interval evaluation gives g(x) ⊆ [1.6071, 1.9001] ⊂ [1.5,2], and we correctly conclude g has a fixed point in [1.6071, 1.9001]. However, ...
- if  $x = [0, 1], \sqrt{x 1} = \sqrt{[-1, 0]}$  evaluates to [0, 0], so  $g(x) = [0.9, 0.9] \subset x$ , for an incorrect conclusion.
- This is due to g not continuous on [0, 1], combined with loose evaluation (returning the range only over the intersection of the domain of g with the interval).
- Loose evaluation is appropriate in other contexts.



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### Taming Interval Dependency Constraint Propagation, Subdivision

## To reduce the overestimation in evaluating an interval expression, we may



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### Taming Interval Dependency Constraint Propagation, Subdivision

# To reduce the overestimation in evaluating an interval expression, we may

Rearrange the expression(s) or systems of equations.



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### Taming Interval Dependency Constraint Propagation, Subdivision

To reduce the overestimation in evaluating an interval expression, we may

Rearrange the expression(s) or systems of equations.

 Use constraint propagation (solving for variables or subexpressions in terms of other variables with known smaller uncertainties)



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### Taming Interval Dependency Constraint Propagation, Subdivision

To reduce the overestimation in evaluating an interval expression, we may

- Rearrange the expression(s) or systems of equations.
- Use constraint propagation (solving for variables or subexpressions in terms of other variables with known smaller uncertainties)
- Subdivide the intervals of uncertainty, compute interval values over these subintervals, and form the union of these interval values.



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To reduce the overestimation in evaluating an interval expression, we may

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- Use constraint propagation (solving for variables or subexpressions in terms of other variables with known smaller uncertainties)
- Subdivide the intervals of uncertainty, compute interval values over these subintervals, and form the union of these interval values.
- Single out dependencies as separate variables.



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To reduce the overestimation in evaluating an interval expression, we may

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- Subdivide the intervals of uncertainty, compute interval values over these subintervals, and form the union of these interval values.
- Single out dependencies as separate variables.
- Use any of many techniques in the literature.



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## Taming Interval Dependency Constraint Propagation, Subdivision

To reduce the overestimation in evaluating an interval expression, we may

- Rearrange the expression(s) or systems of equations.
- Use constraint propagation (solving for variables or subexpressions in terms of other variables with known smaller uncertainties)
- Subdivide the intervals of uncertainty, compute interval values over these subintervals, and form the union of these interval values.
- Single out dependencies as separate variables.
- Use any of many techniques in the literature.
- Cleverly use properties of the specific problem.



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### Available Software Packages for Verified Solution of ODE Systems

COSY-infinity, the cyclotron beam software by Berz and Makino. This is the most successful software for handling input data with wide intervals. However, the old version is no longer distributed and the new version is not yet publicly available. (C / C++ / Fortran)



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- Other generally available codes: Some of these are polished and packaged, but may be practical only for narrow or point input data, to bound computational errors. Two such packages are:



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- Other generally available codes: Some of these are polished and packaged, but may be practical only for narrow or point input data, to bound computational errors. Two such packages are:
  - VNODE-LP (Nedialkov et al, literate programming/C++),
  - ValEnclA-IVP (Rauh, Hofer, Auer, C++, somewhat older)



Usually part of larger libraries

(included in constraint propagation or global optimization packages)

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  - See IEEE-1788-compliant packages in the following.



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### IEEE 1788-2015 Standard for Interval Arithmetic

 Defines basic interval arithmetic, specifying accuracy, required elementary functions, etc.



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### IEEE 1788-2015 Standard for Interval Arithmetic

- Defines basic interval arithmetic, specifying accuracy, required elementary functions, etc.
- Defines an optional binding to the IEEE 754-2008 standard for floating point arithmetic.



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IEEE 1788-2015 Standard for Interval Arithmetic

- Defines basic interval arithmetic, specifying accuracy, required elementary functions, etc.
- Defines an optional binding to the IEEE 754-2008 standard for floating point arithmetic.
- Specifies how extended interval arithmetic is handled, from various special cases.



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Example (The underlying set is  $\mathbb{R}$ , not  $\overline{\mathbb{R}}$ .)

$$\left[\frac{1}{2},\infty\right) \leftarrow \frac{[2,3]}{[0,4]}.$$



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Example (The underlying set is  $\mathbb{R}$ , not  $\overline{\mathbb{R}}$ .)

$$\left[\frac{1}{2},\infty\right) \leftarrow \frac{[2,3]}{[0,4]}.$$

Contains a decoration system for tracking continuity of an expression, if extended interval arithmetic has been used, etc. This can be viewed as a generalization of IEEE 754 exception handling.



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# IEEE 1788-2015 Standard

## Conforming

### Gnu Octave (Matlab-like) by Oliver Heimlich. See http://octave.sourceforge.net/interval/



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# IEEE 1788-2015 Standard

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JInterval (Java) by Dmitry Nadezhin and Sergei Zhilin. See https://java.net/projects/jinterval



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## Conforming

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JInterval (Java) by Dmitry Nadezhin and Sergei Zhilin. See https://java.net/projects/jinterval

C++ by Marco Nehmeier (J. Wolff v. Gudenberg). See https://github.com/nehmeier/libieeep1788



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C++ by Marco Nehmeier (J. Wolff v. Gudenberg). See https://github.com/nehmeier/libieeep1788

### **Conformance in Progress**

ValidatedNumerics.jl (Julia) by David P. Sanders and Luis Benet (UNAM)

See https: //github.com/dpsanders/ValidatedNumerics.jl



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## Interval Arithmetic Packages Good non-conforming packages

In many applications, full implementation of the IEEE standard is not needed.



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For example, in simple calculations, the decorations (exception handling) and extended arithmetic would not play a part.



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Interval Arithmetic Packages Good non-conforming packages

In many applications, full implementation of the IEEE standard is not needed.

For example, in simple calculations, the decorations (exception handling) and extended arithmetic would not play a part.

 For efficiency, ease of implementation, or other reasons, some packages are not totally conforming.
 Siegfried Rump's INTLAB is one widely-used such package.



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- to tell me about your work.



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#### Practical Pitfalls

#### Practical Software

ODE Packages Existence Verification The IEEE Standard

#### conclusion

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- for details,
- for advice,
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- to tell me about your work.

### See

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#### Histor

Early Moore Others

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**Questions?**